



P133 MID STROKE LINEAR POSITION SENSOR

Position feedback for industrial and scientific applications

Dimensions

- Non-contacting inductive technology to eliminate wear
- Travel set to customer's requirement
- Short body length
- High durability and reliability
- High accuracy and stability
- Sealing to IP65/IP67 as required

As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Positek $^{\circledR}$ has the expertise to supply a sensor to suit a wide variety of applications.

Our P133 is an affordable, durable, accurate position sensor designed for a wide range of industrial applications. It is particularly suitable for OEMs seeking good sensor performance in situations where a short-bodied sensor is needed and cost is important. The unit is compact and space-efficient, being responsive along almost its entire length, and like all Positek® sensors provides a linear output proportional to travel. Each unit is supplied with the output calibrated to the travel required by the customer, from 51 to 100mm and with full EMC protection built in.

Overall performance, repeatability and stability are outstanding over a wide temperature range. The sensor has a rugged stainless steel body and plunger. It is easy to install and set up, mounting options include flange, M5 rod eye bearings and body clamps. The plunger can be supplied free or captive, with a female M4 thread, an M5 rod eye, magnetic tip, or spring-loaded with a dome end. The P133 also offers a wide range of mechanical and electrical options, environmental sealing is to IP65 or IP67 depending on selected cable or connector options.



SPECIFICATION

Difficusions					
Body diameter	35 mm				
Body Length Dependant on calibrate	ed travel & mounting	option			
Calibrated Travel	Standard	Flange mounted			
Axial version		•			
51 mm to 70 mm	125 mm	141.3 mm			
71 mm to 100 mm	155 mm	171.3 mm			
Radial version					
51 mm to 70 mm	143.5mm	159.8 mm			
71 mm to 100 mm	173.5 mm	189.8 mm			
Plunger	Ø 6mm				
For full mechanical details see dra					
Independent Linearity					
Temperature Coefficients					
	$< \pm 0.01\%FS/^{\circ}$				
Frequency Response	> 10 kHz (-3dB				
		s) 2 wire 4 to 20 mA			
Resolution	Infinite				
Noise	< 0.02% FSO				
Environmental Temperature					
Operating	-40°C to +125°				
_	-20°C to +85°C				
Storage	-40°C to +125°				
Sealing		nding on connector / cable option			
EMC Performance	EN 61000-6-2,				
Vibration	IEC 68-2-6:				
Shock	IEC 68-2-29:				
MTBF	350,000 hrs 40	°C Gf			
Drawing List					
P133-11	Sensor Outline				

3D models, step or .igs format, available on request.

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs please contact us with your requirements.



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How Positek's technology eliminates wear for longer life

Positek's Inductive technology is a major advance in displacement sensor design. Our displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

Our technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A Positek sensor, based on simple inductive coils using Positek's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

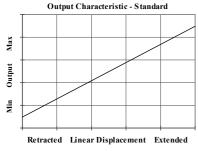
It also overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials, no requirement for separate signal conditioning.

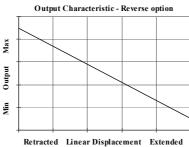
We also offer a range of ATEX-qualified intrinsically-safe sensors.

D122		a	b	С	d	е	f	g	h	j	k	
P133	•	Displacement	Output	Adjustments	Connections	Option	Option	Option	Option	Option	Z-code	

a Displacement		Value		
Factory set to any lengt (e.g. 0-76 mm)	h from 0-51 mm to 0-100 mm	76		
b Output				
$\begin{array}{c} \text{Supply V}_{\text{dc}} \\ \text{(tolerance)} \end{array}$	Output	Code		
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	A		
±15V nom. (±9 - 28V)	±5V	В		
+24V nom. (13 - 28V)	0.5 - 9.5V	C		
±15V nom. (±13.5 - 28V)	±10V	D		
+24V nom. (18 - 28V)	4 - 20mA 2 wire	E		
+24V nom. (13 - 28V)	4 - 20mA 3 wire Sink	F		
+24V nom. (9 - 28V) 0.5 - 4.5V		G		
+24V nom. (13 - 28V)	4 - 20mA 3 wire Source	Н		
Supply Current: 'A' 10mA nomin max. 'F' & 'H' 32mA nominal, 35	nal, 12mA max. `B', `D' & `G' 12mA nominal, 15mA n 5mA max.	nax. 'E' 26mA		
c Calibration Adjust	ments	Code		
Accessible default [†]	[†] Axial version only. Radial version sealed by	blank		
Sealed default. Y		Y		
d Connections		Code		
Cable gland radial IP67	Pg9, metal	Ixx		
Connector axial IP65 4 pin (3+earth) DIN 43650 'C'				
Connector axial IP65 4 pin (3+earth) DIN 43650 'C', pre-wired Jxx				
Connector radial IP67 4 pin M12 IEC 61076-2-101, nylon				
Connector radial IP67 4 pin M12 IEC 61076-2-101, nylon, pre-wired Kxx				
Cable gland axial IP67 M12, nylon				
Cable gland, short [†] axial IP67, metal Mxx				
Specify required cable length 'x cable, 50 cm supplied as standa	$\mathbf{x'}$ in cm. e.g. L2000 specifies axial cable gland with ard. † Nb: restricted cable pull strength.	1 20 m of		

e Housing	Code		
Standard default			
Flange Mount 2 off 4.5 mm x 30 degree wide slots, 48 mm P.C.D.			
M5 Rod-eye bearing radial version only			
f Body Fittings	Code		
None default	blank		
Body Clamps 1 pair	P		
g Sprung Plunger			
Not sprung default			
Spring extend captive plunger only. Note! Supplied loose without option 'T'			
h Plunger Fittings	Code		
Female thread M4x0.7x7 deep default			
Dome end with spring extend option 'R'			
M5 Rod-eye Bearing			
Magnetic Tip			
j Plunger Code			
Captive plunger is retained - default	blank		
Non-captive plunger can depart body			
k Z-code (optional)			
Option 'J' with IP67 M12 IEC 61076-2-101 conn. No access to cal. Adjustments, must include option 'Y'	Z600		
Option `J' with IP67 M12 IEC 61076-2-101 conn. with access to cal. adjustments			
≤± 0.1% FSO @20°C Independent Linearity			
31 0.1 % 130 @20 C Independent Linearity			
1/4" Rod eyes with options 'S' and/or 'U'	Z827		



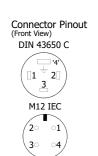


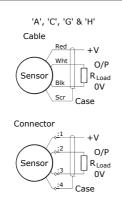
For further information please contact: www.positek.com sales@positek.com

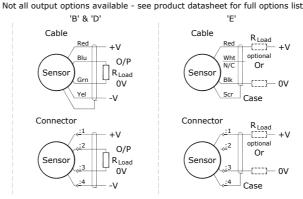


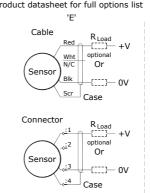
Installation Information P133 MID STROKE LINEAR POSITION SENSOR

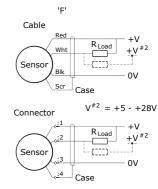
Output Option	Output Description:	Supply Voltage: V _s (tolerance)	Load resistance: (include leads for 4 to 20mA O/Ps)
A	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	≥ 5kΩ
В	±5V	±15V nom. (±9 - 28V)	≥ 5kΩ
С	0.5 - 9.5V	+24V nom. (13 - 28V)	≥ 5kΩ
D	±10V	±15V nom. (±13.5 - 28V)	≥ 5kΩ
E	4 - 20mA 2 wire Current Loop	+24V nom. (18 - 28V)	≈ 0 - 300Ω max. @24V ~ 1.2 to 6V across 3000 $~\{R_L$ max. = (V_s - 18) / $20^{\text{-3}}\}$
F	4 - 20mA 3 wire Sink	+24V nom. (13 - 28V)	≈ 0 - 950 Ω max. @24V ~ 3.8 to 19V across 950 Ω {RL max. = (Vs - 5) / 20^{-3} }
G	0.5 - 4.5V	+24V nom. (9 - 28V)	≥ 5kΩ
Н	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	≈ 0 - 300Ω max. ~ 1.2 to 6V across 300Ω











Gain and Offset Adjustment: (Where accessible - Typically \pm 10% Min available) To adjust the gain or offset use a small potentiometer adjuster or screwdriver 2mm across. Do not apply too much force on the potentiometers.

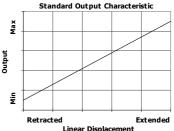
Calibration Adjustments

Mechanical Mounting: Depending on options, body can be mounted by flange, rod eye bearing or clamping the sensor body - body clamps are available, if not already ordered. Plunger mounted by M4x0.7 female thread, rod-eye bearing or magnetic tip - see drawing P133-11.

Output Characteristic: Plunger extended by, at start of normal travel:

Standard: 42.5 mm* from Ø35 mm face Flange Mount: 28 mm* from flange face *Note: where ball end option is fitted add 5 mm.

The output increases as the plunger extends from the sensor body, the calibrated stroke is between 51 mm and 100 mm.



Warning - The M12 IEC connector may be rotated for purposes of convenient orientation of the connector and cable, however rotating the connector more than one complete revolution is not recommended. Repeated rotation of the connector will damage the internal wiring!

Incorrect Connection Protection levels:

Not protected – the sensor is not protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the supply current is limited to less than 50mA.

B & D Supply leads diode protected. Output must not be taken outside \pm 12V. Supply leads diode protected. Output must not be taken outside 0 to 12V. C & G

E, F & H Protected against any misconnection within the rated voltage.